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53 (IE 810) VINS

2018

VIRTUAL INSTRUMENTATION

Paper : IE 810

Full Marks : 100

Time : Three hours

The figures in the margin indicate full marks for the questions.

Symbols have their usual significance.

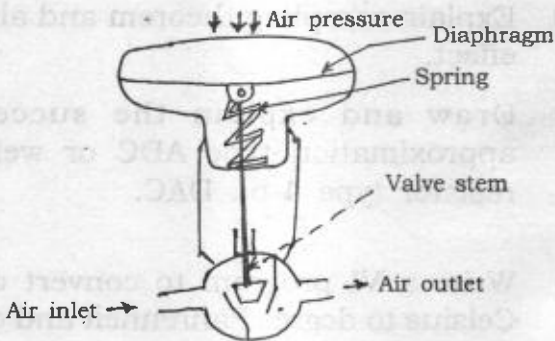
Answer **any five** questions.

1. (a) What is Virtual Instrumentation ?
Mention the advantages of Virtual Instrumentation. 6
- (b) Explain sampling theorem and aliasing effect. 4
- (c) Draw and explain the successive approximation type ADC or weighted resistor type 4-bit DAC. 10
2. (a) Write a VI program to convert degree Celsius to degree Fahrenheit and degree Fahrenheit to degree Celsius. 10

Contd.

(b) What is Sub VI? Explain how the Sub VI can be reused to solve the quadratic equations. 10

3. Pneumatically controlled valves are operated by changing the air pressure to a diaphragm, as illustrated in Fig#3. The pressure, acting on the area of the diaphragm, generates a force that attempts to move the valve stem :
- $$F_{Air} = PA.$$
- That force is countered by a spring that pushes on the diaphragm in the other direction : $F_{Spring} = K_{Spring} x$ where K_{Spring} is the spring constant and x is the extension of the spring. Control valve typically use air pressures ranging between 3 *psi* and 15 *psi*. The change in applied force because of the pressure change causes the valve stem to move approximately 1 *inch*.



Fig#3

Determine

- (a) The force applied to a 10 inch diameter diaphragm by 3 psi air.
- (b) The force applied to a 10 inch diameter diaphragm by 15 psi air.
- (c) The change in applied force (ΔF) as the air pressure increases from 3 to 15 psi.
- (d) The spring constant required to cause the valve stem to move 1 inch in response to the calculated change in force.

Write the VI programs for the above problem. 20

- 4. (a) Explain the FOR Loop and WHILE Loop. Give one example for each case. 10
(b) Write the VI programs to perform the determinant and transpose of a given matrix. 10
- 5. (a) What is data acquisition system (DAS)? Explain the computer based DAS with a block diagram. 10

- (b) Explain how DAS can be designed and developed using Labview. Mention at least *four* important parameters that to be set during VI program. 10
6. (a) What are the features of RS 485 and RS 422 ? 6
- (b) Mention and explain the different buses. 6
- (c) Explain in detail about the different USB standards. 8
7. (a) Write a VI program for BMI (Basic Metabolic Index) representation along with both digital & analog (by slide pointer) indication. Indicate the result in front panel for Mr. X having weight (W) = 180 lb and height (h) = 5 ft. 3 in. and also check whether Mr. X remains in NORMAL BMI range or NOT. If he is not in normal BMI range then what amount of weight is to be reduced gained for normal BMI.

$$\text{Assume : } BMI = \frac{4.88 * M(\text{lb})}{H^2(\text{ft}^2)}$$

BMI = Underweight when $BMI < 18.5$.
 Normal weight when $BMI = 18.5 - 25$.
 Overweight when $BMI = 25 - 30$ and
 Obese when $BMI > 30$.

10

(b) Write a VI program to simulate a PID controller. 10

8. Write short notes on **any four** of the following: 4×5=20

(a) Auto indexing array

(b) CRIO and MyRIO devices

(c) R-2R type 4-bit DAC

(d) Role of range and resolution in DAS

(e) RS 232 and RS 422

(f) Array and clusters.

Write a VI program to simulate a PID controller.

Write short notes on any four of the following:

- (a) Auto indexing logic
- (b) CPIO and MPIO devices
- (c) R-2R type 4-bit DAC
- (d) Role of range and resolution in DAC
- (e) RS 232 and RS 422
- (f) Array and clusters