

Total number of printed pages—6

53 (IE 712) CCPR

2014

COMPUTER CONTROL OF PROCESS

Paper : IE 712

Full Marks : 100

Pass Marks : 30

Time : Three hours

The figures in the margin indicate full marks for the questions.

Answer any five questions out of seven.

1. (a) A discrete-time system is described by the state equation

$$y(k+2) + 5y(k+1) + 6y(k) = u(k)$$

Determine the state model in canonical form. 5

- (b) Determine the stability of sample-data control system having following characteristics equation

$$2z^6 + 2z^5 + 5z^4 + 7z^3 + 10z^2 + 4z + 1 = 0$$

5

Contd.

- (c) A continuous-time plant of a sampled data system is described by the state equation

$$\dot{x} = \begin{bmatrix} 0 & 2 \\ -4 & 0 \end{bmatrix} x + \begin{bmatrix} 0 \\ 2 \end{bmatrix} u$$

Determine the value of sampling period T , which make the system uncontrollable.

10

2. (a) Find the Z transform of the following :
(any two) 8

(i) $f(t) = 2u(t) + t$

(ii) $e^{-at} \sin wt$

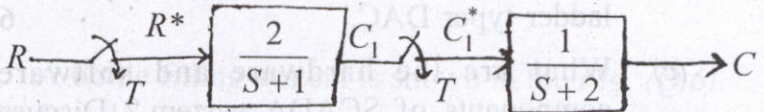
(iii) t^2

- (b) Find the inverse Z transform of the following : 8

(i) $\frac{z}{(z+1)(z+2)}$

(ii) $\frac{2-0.4}{z^2+z+2}$

- (c) Determine pulse transfer function for the sampled data control system shown in Fig.2(c). 4



3. The block diagram of a sampled-data control system is shown in the drawing of Fig (Q.3). The sampling period is $\Delta t = 1 \text{ min}$.

- (a) Design the digital controller $D(z)$ so that closed-loop system exhibits a minimal prototype response to a unit step change in the load variable L .
- (b) Design a digital PID controller based on the ITAE (set point) criterion and examine its performance for a step change in the set point. 20

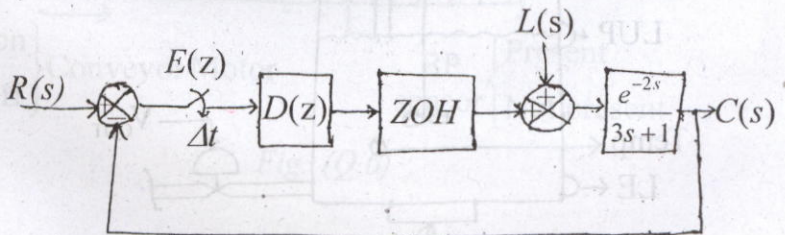


Fig. (Q.3)

4. (a) What is data acquisition? Describe the data acquisition system with neat and proper block diagram. 8
- (b) Discuss briefly the operation of a R-2R ladder type DAC. 6
- (c) What are the hardware and software components of SCADA system? Discuss them briefly with neat sketch. 6
5. (a) What is PLC? Explain the operation of PLC with block diagram. 2+8
- (b) Draw a ladder diagram for the control problem shown in Fig. (Q.5b). The global objective is to heat a liquid to a specified temperature and keep it there with stirring for 30min. The hardware has the following characteristics

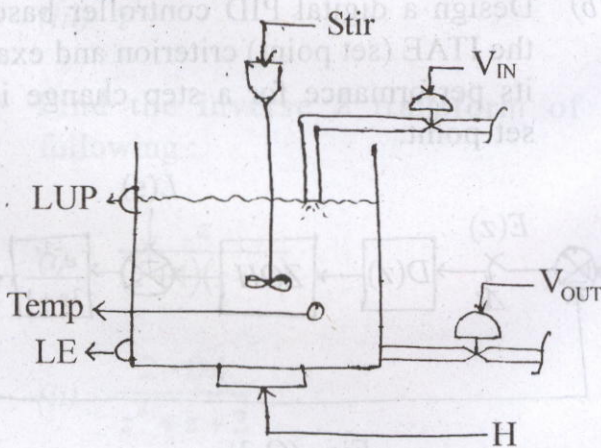


Fig. (Q.5b)

(i) START push button is NO, STOP is NC.

(ii) NO and NC are available for the limit switches. 10

6. A bottle filling system is shown in the Fig. (Q.6). Develop a ladder diagram to run the process.

20

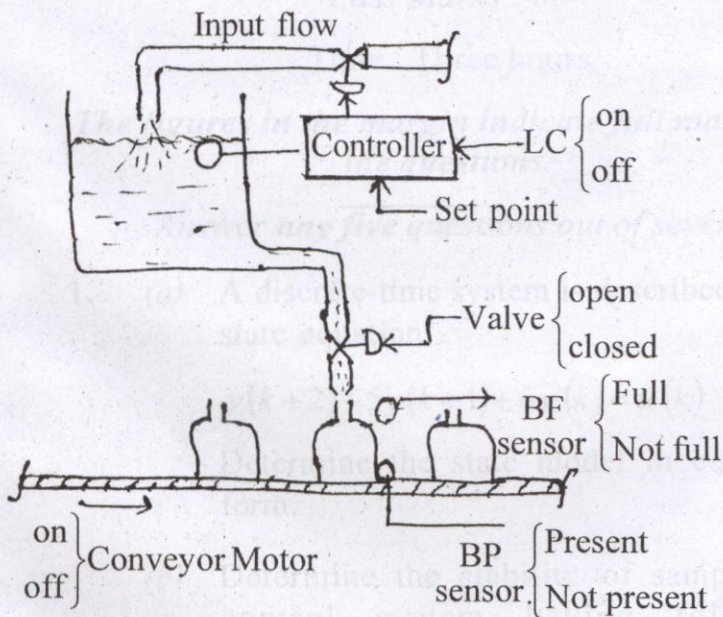


Fig. (Q.6)

7. Write short notes on : (any four)

4×5

- (a) Genetic algorithm
- (b) Dahlin's algorithm
- (c) Relay Vs PLC
- (d) Digital PID controller
- (e) Fuzzy Logic.

