

Total number of printed pages-11

53 (EC 603) DISP

2018

DIGITAL SIGNAL PROCESSING

Paper : EC 603

Full Marks : 100

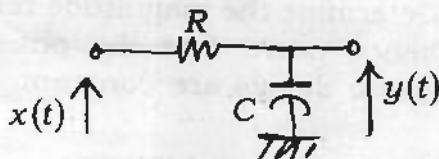
Time : Three hours

The figures in the margin indicate full marks for the questions.

Answer any five questions.

- (a) Establish the relation between analog and digital frequency. 5

(b) In the given low-pass RC circuit shown below with $R=1M\Omega$ and $C=1\mu F$, determine the equivalent discrete-time expression for the circuit response $y(n)$ when the input is given by $x(t) = \exp(-2t)$, and the sampling frequency is 50Hz. 15



Contd.

2. (a) Find the impulse response $h(n)$ for each of the causal, discrete-time LTI systems satisfying the following difference equations and also indicate whether each system is FIR or IIR system : 5×3=15

(i) $y(n) = x(n) - 2x(n-2) + x(n-3)$

(ii) $y(n) + 2y(n-1) = x(n) + x(n-1)$

(iii) $y(n) - 0.5y(n-2) = 2x(n) - x(n-2)$

- (b) Find the z-transformation of (i) $x(n) = 1$

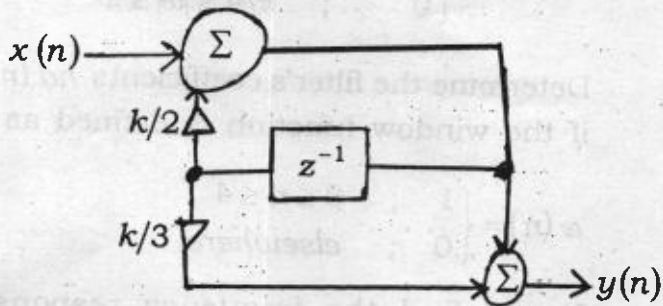
(ii) $x(n) = 2^n u(n-2)$. 5

3. (a) An FIR filter ($N = \Pi$) is characterised by the following transfer function :

$$H(z) = \sum_{n=0}^{N-1} h(n)z^{-n}$$

Determine the magnitude response and hence prove that the phase and the group delays are constant. 10

- (b) Consider the discrete-time system shown below. For what values of 'k' is the system BIBO stable? 10



4. (a) Design a single-pole low pass digital filter with a 3dB bandwidth of 0.2π using bilinear transformation. The analog filter has a system response given by

$$H(s) = \frac{\Omega_c}{s + \Omega_c} ; \text{ where '}\Omega_c\text{' is the } 3\text{dB bandwidth of the analog filter.}$$

10

- (b) A digital low pass filter is to be designed with the following desired frequency response : 10

$$H_d(\omega) = \begin{cases} e^{-j\omega \times 2} & ; \quad -\pi/4 \leq \omega \leq \pi/4 \\ 0 & ; \quad \pi/4 \leq |\omega| \leq \pi \end{cases}$$

Determine the filter's coefficients $hd(n)$ if the window function is defined as

$$w(n) = \begin{cases} 1 & ; \quad 0 \leq n \leq 4 \\ 0 & ; \quad \text{elsewhere} \end{cases}$$

Hence find the frequency response $H(\omega)$ of the designed filter.

5. (a) Determine the lowest order of a transfer function $H_a(s)$ having maximally flat low pass characteristics with a 1dB cutoff frequency at 1kHz and a minimum attenuation of 40dB at 5kHz. 8

- (b) Design a digital LPF (Butterworth) using impulse invariant method to meet the following specifications : 12

- (i) Pass band edge frequency
= 1.25kHz

- (ii) Stop band edge frequency
= 2.75kHz.
- (iii) Pass band ripple $\leq 0.5\text{dB}$
- (iv) Stopband attenuation $\geq 15\text{dB}$
Sampling frequency is 10kHz.
6. (a) Compute the DFT of the sequence
 $x(n) = \{4, 4 + 3i, 2, -4\}$ 8
- (b) Draw the complete signal flow graph of
8 point DIF-FFT algorithm. 12
7. (a) Draw the block diagram of linear
convolution using DFT. 6
- (b) What are the major factors that
influence our choice of a specific
realisation? 6
- (c) Write a short note on Frequency
sampling realisation of FIR filter. 8
8. (a) Develop a Direct Form II structure with
combined common delay for the
following: 10
- $$y(n) = 2x(n) - 3x(n-1) - x(n-2) + 1.5x(n-3)$$
- $$+ 5x(n-4) - 2.5y(n-1) + 2y(n-2) - 1.5y(n-3).$$

(b) A digital system is given with the difference equation .

$y(n) = 0.9y(n-1) + x(n)$ with $x(n) = 0$ and initial condition $y(-1) = 4$. Explain zero input limit cycle effect. 10

9. (a) Find the circular convolution $y_c(n) = x(n) * h(n)$ where

$$x(n) = \{1, -2, 4, 15\} \text{ and } h(n) = \{3, 0, -2, 5\}$$

(b) Consider the transfer function of an analog filter $H(s) = (s+3)/s^2 + 4s + 13$. Now design the corresponding digital filter using impulse invariant method, consider sampling time = 0.1s. 10

(c) A system has impulse response given by $h(n) = -0.25\delta(n+1) - 0.5\delta(n) + 0.25\delta(n-1)$. Is the system causal? 3

10. (a) Find the inverse z-transform of

$$X(z) = \frac{z(z^2 - 4z + 5)}{(z-3)(z-1)(z-2)}$$

for ROC (i) $2 < |z| < 3$, (ii) $|z| < 1$

10

- (b) What are the advantages of digital filters over analog filters? 5
- (c) Why are FFT techniques so important in DSP? 5
11. (a) What are the desirable and undesirable features of FIR filters? 5
- (b) Why FIR filters are known as all-zero filters? 5
- (c) Write short notes on *any two* from the following: 5+5
- (i) Gibbs phenomenon
- (ii) Overlap-add and Overlap-save methods
- (iii) Design of FIR filter using window method.

12. Multiple choice type questions.
Choose the correct alternative: $10 \times 2 = 20$

- (i) The output of a causal system:
- (a) does not depend on the input
- (b) depend on the present and future input

- (c) does not depend on future input
- (d) does not depend on the past and future input.
- (ii) Advantage of DSP over analog signal processing is :
- (a) greater accuracy
- (b) flexibility in configuration
- (c) digital realisation is cheaper
- (d) all of these.
- (iii) The system $y(n) = x(n) + 3x(n-1)$ is
- (a) static
- (b) linear
- (c) dynamic
- (d) non-linear
- (iv) The system $y(n) = x(n) + nx(n-1)$ is
- (a) non-causal and time invariant
- (b) causal and time variant
- (c) causal and time invariant
- (d) non-causal and time variant.

(v) Which of the following is N -point DFT of $x(n)$:

$$(a) \quad X(k) = \sum_{k=0}^{N-1} x(n) \exp(-j2\pi kn \times N)$$

$$(b) \quad X(k) = \sum_{k=0}^{N-1} x(n) \exp(-j2\pi kn / N)$$

$$(c) \quad X(k) = \sum_{k=0}^{N-1} x(n) \exp(+j2\pi kn / N)$$

(vi) The Fourier transform of a discrete and periodic sequence is —

- (a) discrete and periodic
- (b) continuous and periodic
- (c) continuous and aperiodic
- (d) discrete and aperiodic.

(vii) Which of the following error (s) arise (s) due to quantisation of numbers ?

- (a) Input quantization error
- (b) Product quantisation error
- (c) Coefficient quantisation error
- (d) All of these.

(viii) Which of the following is not a power signal ?

- (a) unit step
- (b) $\exp(j\omega_0 n)$
- (c) periodic sequence
- (d) unit ramp sequence.

(ix) Consider an analog signal $x_a(t) = 3\cos 100\pi t$. The min. sampling rate required to avoid aliasing is

- (a) 100Hz
- (b) 200Hz
- (c) 50 Hz
- (d) 75 Hz.

- (x) Zero padding indicates :
- (a) Zeros appearing in $X(k)$ sequences
 - (b) Value of $X(k)$ are zero
 - (c) Dummy zero valued samples added
 - (d) None of these.
-

- (a) Zero padding indicators:
- (b) Zeros appearing in $X(k)$ sequences
- (c) Value of $X(k)$ are zero
- (d) Dummy zero valued samples added
- (e) None of these