

Total number of printed pages - 7

53 (EC 302) SISY

2014

LINEAR SYSTEMS AND SIGNALS

Paper : EC 302

Full Marks : 100

Pass Marks : 30

Time : Three hours

The figures in the margin indicate full marks for the questions.

Answer any five questions.

1. (a) Determine whether the following signals are energy or power signal $2 \times 3 = 6$

(i) $x(t) = \sin^2 w_0 t$

(ii) $x(t) = \text{rect}(t/\tau)$

(iii) $x(t) = A e^{-at} \cdot u(t); a > 0$

Contd.

(b) Sketch the following : 2+2=4

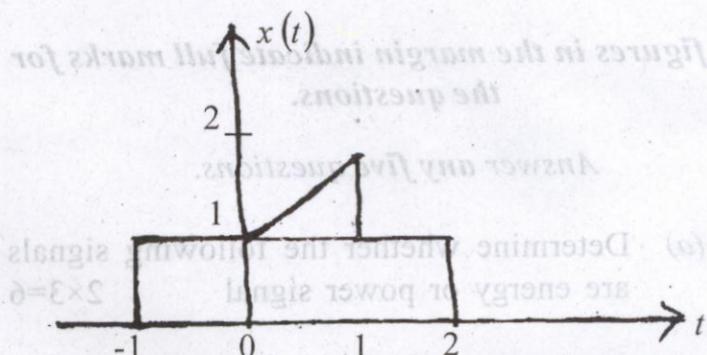
(i) $2u(t+2) - 2u(t-3)$

(ii) $r(t) - r(t-1) - r(t-3) + r(t-4)$

(c) For the signal $x(t)$ shown find the signal

(i) $x(5/3t)$

(ii) $x\left(\frac{1}{2}t - 2\right)$



(d) Find even and odd components of the following : 2+2=4

(i) $x(t) = e^{j\omega t}$

(ii) $x(n) = \{-3, 1, 2, -4, 2\}$

10 (e) Find whether the signal $x(t) = u(t+2) - u(t-2)$ is causal or non-causal signal. Give reason for your answer.

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2. (a) Define Fourier series. Give Dirichlet conditions for Fourier series.

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(b) Find the complex exponential Fourier series representation of the following signals

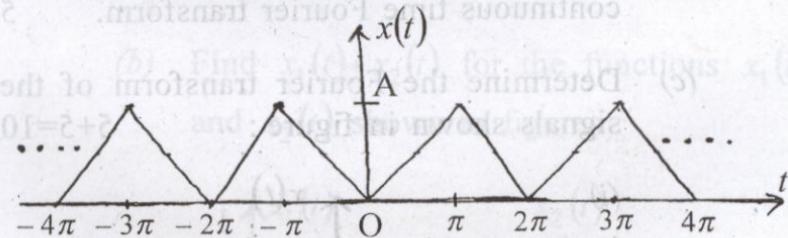
5

$$(i) \quad x(t) = 4 \cos 2\omega_0 t$$

$$(ii) \quad x(t) = 3 \sin 4\omega_0 t$$

(c) Find the Fourier series expansion for the waveform shown below:

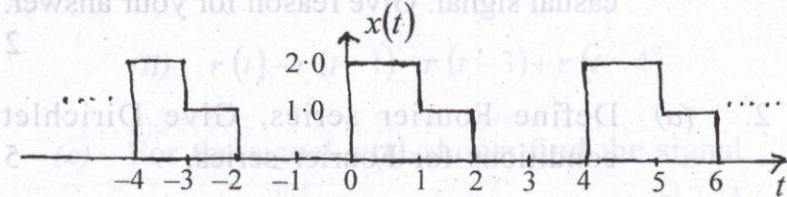
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3. (a) What are orthogonal functions? Prove that the complex exponential signals are orthogonal function.

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- (b) Compute the exponential Fourier series of the signal shown in the figure. 10



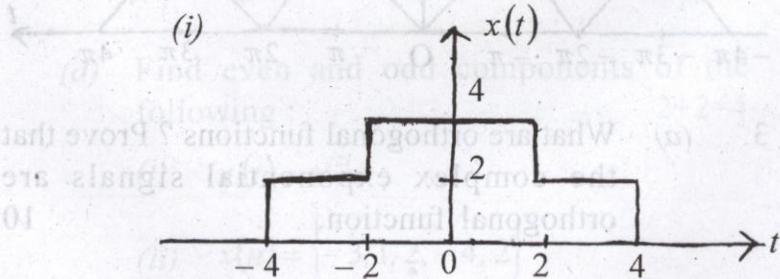
4. (a) Using properties of Fourier transform, find the Fourier transform of the following : 5

$$(i) \quad x(t) = u(-t)$$

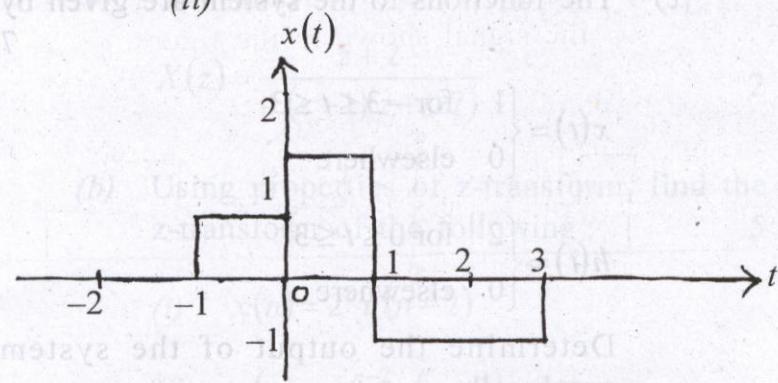
$$(ii) \quad x(t) = \delta(t+2) + \delta(t+1) + \delta(t-1) + \delta(t-2)$$

- (b) State and prove Parseval's Relation for continuous time Fourier transform. 5

- (c) Determine the Fourier transform of the signals shown in figure : 5+5=10



(ii)

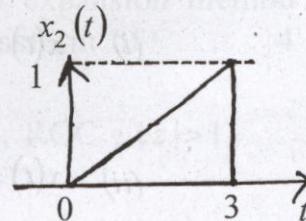
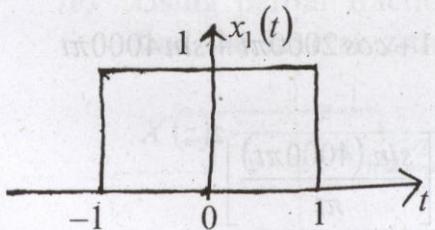


5. (a) Find the convolution of the following signals : 3+3=6

$$(i) \quad x_1(t) = e^{-2t}u(t) ; \quad x_2(t) = e^{-4t}u(t)$$

$$(ii) \quad x_1(t) = t.u(t) ; \quad x_2(t) = t.u(t)$$

(b) Find $x_1(t)*x_2(t)$ for the functions $x_1(t)$ and $x_2(t)$ shown in figures 7



(c) The functions to the system are given by

7

$$x(t) = \begin{cases} 1 & \text{for } -3 \leq t \leq 3 \\ 0 & \text{elsewhere} \end{cases}$$

$$h(t) = \begin{cases} 2 & \text{for } 0 \leq t \leq 3 \\ 0 & \text{elsewhere} \end{cases}$$

Determine the output of the system graphically.

6. (a) State sampling theorem. Explain different types of sampling techniques. 8

(b) What do you mean by interpolation ? Name the methods used to reconstruct signals. Obtain the transfer function of zero order hold. 8

(c) Find the Nyquist rate and Nyquist sampling interval for the following signals : 4

$$(i) \quad x(t) = 1 + \cos 2000\pi t + \sin 4000\pi t$$

$$(ii) \quad x(t) = \left[\frac{\sin(4000\pi t)}{\pi t} \right]^2$$

7. (a) Find $x(\alpha)$ if

$$X(z) = \frac{z+2}{4(z-1)(z+0.7)} \quad 2$$

(b) Using properties of z-transform, find the z-transform of the following : 5

$$(i) \quad x(n) = 2^n u(n-2)$$

$$(ii) \quad x(n) = \alpha^{n-2} u(n-2)$$

(c) Find z-transform and ROC of

$$x(n) = a^n u(n) - b^n u(-n-1) \quad 6$$

Sketch the ROC and pole-zero location.

(d) Using long division, determine the inverse z-transform of 3

(a) $X(z) = \frac{z}{2z^2 - 3z + 1}$; ROC ; $|z| > 1$

(e) Using partial fraction expansion method find the inverse z-transform of 4

$$X(z) = \frac{z^{-1}}{3 - 4z^{-1} + z^{-2}} ; \text{ROC} ; |z| > 1$$
