

2025

**Industrial Automation***Full Marks: 100: Time: Three hours**The figures in the margin indicate full marks for the questions.**Answer any 05 questions out of 07.*

- 01 A Write the full form of LASER, RTS, JPG,PNG,MAC, TCP,EBCDIC, WWW, CTS, PID. 10
- B What is mean by automation? Why automation is required for the industrial process? 05
- C Draw and derive the expression of negative feedback. what are the advantages of negative feedback? 05
- 02 A Define the Robotic arm terminology: Link, Joint, Degrees of freedom, Tool centre point, workspace. 10
- B Write the major application areas of robotic system. 05
- C Define forward and inverse kinematics with the help of an example. 05
- 03 A What are the seven different layers of OSI model explain the working of each layer in short? 10
- B Draw AND circuit, Draw Its relay circuit. Also draw its LADDER logic diagram. Finally draw PLC circuit. 05
- C Draw the figure of Optocoupler. 05
- 04 A Write a short note on: (a) Field bus (b)Fibre optics, 10
- B Draw 3-bit Flash type ADC. 05
- C What is PID controller. Write down its equation. 05
- 05 A Draw the block diagram of Successive approximation type ADC. Explain with 10
- B Draw electromechanical relay with two connectors. 05
- C Draw and label counter type ADC. 05
- 06 A The links of a 3R robotic arm are  $L_1 = 100$  mm,  $L_2 = 250$  mm and  $L_3 = 50$  mm. The gripper is at world coordinates given as  $x = 200$  mm,  $y = 300$  mm and  $\alpha = 30^\circ$ . Determine the angles  $\theta_1$ ,  $\theta_2$  and  $\theta_3$ , which the motor controlling the shoulder, elbow and wrist to be rotated. 10
- B What are the three Laws of Robotics? Mention the safety issues in robot usage. 05
- C What are the different subsystems of a robotic system? Discuss them briefly. 05
- 07 A Draw the block diagram of Digital data acquisition system and explain shortly about each block. 10
- B What is Optocoupler? Why it is used in electronic circuits. 05
- C Function of data link. 05