2023

Control Systems and PLC

Full Marks: 100

Time: Three hours

The figures in the margin indicate full marks for the questions.

Utilize graph paper and semi-log paper as needed for the questions in the exam. Please note that these materials will be provided by the invigilator. Answer **any five** questions.

		nπin	
1.		Using the Routh Hurwitz criterion comment on the stability of the	5+5+5+5=
		following system for which the open loop transfer function is	20
		$A) G(s)H(s) = \frac{2}{s+2}$	
		B) $G(s)H(s) = \frac{2}{s^2(s+2)}$	
		C) $G(s)H(s) = \frac{2}{s(s+2)}$	
		D) $G(s)H(s) = \frac{2(s+1)}{s(s+2)}$	
		असतो मा सत गमय	
2.	a	Highlight the key difference among the following methods of analyzing the stability of a control system in frequency domain. a) Routh Hurwitz Criterion b) Root Locus c) Nyquist plot d) Bode plot	10
	b	(i) Why do we need a semi log paper for Bode plot? Highlight the importance of	5+5
		semi log axis.	
		(ii) For open loop transfer function $G(s)H(s)=(s+1)$ take at least 5 values of s in s-plane and draw the corresponding values in $G(s)H(s)$ -plane.	
		- France and and the corresponding values in Glassials.	
			2

3.	For the following open loop transfer function draw the Nyquist plot by	20
	generating at least five points in $G(s)H(s)$ -plane also comment on the	20
	stability of the control system.	
	swoming of the control system.	
	$G(s)H(s) = \frac{1}{s(s+1)}$	
4.	A unity feedback control system has an open loop transfer function	20
	$G(s)H(s) = \frac{K}{s(s+4)}$	20
	Draw the root locus and determine the value of K , if the damping ration ζ =0.707.	
5.	Construct the Bode plot of the system for which the open loop transfer	20
	function is	
	$G(s)H(s) = \frac{4}{s(1+0.5s)}$	
	Also comment on the stability of the control system based on the values of gain margin and phase margin.	
6.	The open loop transfer function of a unity feedback control system is given	20
	by	
	$G(s) = \frac{K}{s(sT_1 + 1)(sT_2 + 1)}$	
	$s(sT_1+1)(sT_2+1)$	
	Applying Routh Hurwitz criterion determine the value of K in terms of T1	
	and T2 for the system to be stable.	
	ESTD - 2006	

असतो मा सत गमय तमसो मा ज्योतिर्गमय