Printed pages:2 Programme (Dip)/ 4th Semester/ DECE 401 2025

Microcontroller and Applications

Full Marks: 100

Time: 3 hours

The figures in the margin indicate full marks for the questions. Answer any five questions.

1 a) Write an assembly program for copying a block of 5 bytes of data available [6] from address 60H to 65H to the location starting from 40H to 45H. b) For a crystal frequency of 11.0592 MHz, find the value to be loaded into [4] TH1 for Baud rates of 600 and 150. Kokrajhar:: Bodoland c) Write an assembly code to read the content of external RAM locations [6] 10F4H and 10F5H and place the values read in R6 and R7, respectively. Write a short note on the register: program counter. [4] a) Write the assembly language instructions to add two 16-bit numbers: 143Ah, 2 [8] A02Fh. [8] b) Write a program to read the status of the switch, and send it to control the LED as shown in Figure. Provide a comparison between the different unconditional jump instructions. [4] 3 Write a program using Timer 0 to create a 10 kHz square wave on P1.0 [8] a) Write a program to transmit an ASCII character 'Z' continuously with a baud [8] rate of 1200 with a crystal frequency of 11.0592MHz. c) Explain the mode 2 operation for timer T0 with necessary block diagram. [4] 4 Store the string "SUMMER2025" in the look up table with starting address [10]

100H. Write a program to read the string, one character at a time and send it

to display port P1.

	b)	Write the process of interrupt execution in Intel 8051 MCU	[5]
	c)	Read port P0 and send its value on port P2 hundred times.	[5]
5	a)	Write a program to add contents of ten memory locations from 20H onwards. Store the final result at 40H in the RAM.	[4+6]
	b)	Draw the diagram of Intel 8051 MCU being connected to an RS 232 port through a DB9 Connector.	[5]
	c)	Mention the addressing modes of the Intel 8051 MCU, give two examples for each mode.	[5]
6.	a)	Two numbers are stored in registers: R0, R1. Verify if their sum is greater than FFh.	[5]
	b)	Write a program to read the port P0. If its value is greater than 50H, then set P1.0 else set P2.0.	[5]
	c)	Write a program to receive the data, which has been sent in serial form and send it to the output port P0 in parallel form.	[10]

