

Total No. of printed pages = 5

CAI-501/CS/5th Sem/2016/N

CONTROL SYSTEMS

Full Marks – 70

Pass Marks – 28

Time – Three hours

The figures in the margin indicate full marks
for the questions.

Answer any *five* questions.

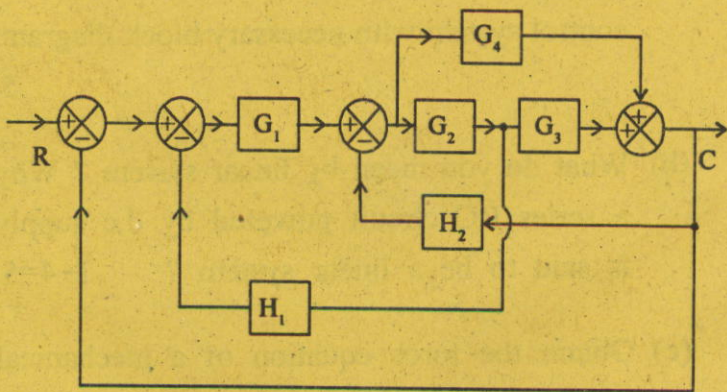
1. (a) Describe the operation of an automatic control system with necessary block diagram. 5

- (b) What do you mean by linear system ? Why a series RC circuit powered by d.c supply is said to be a linear system ? 1+4=5

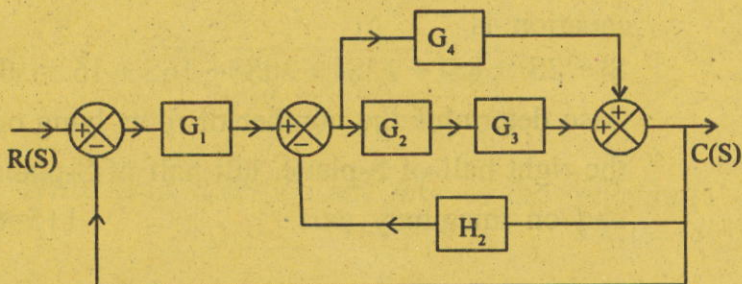
- (c) Obtain the force equation of a mechanical accelerometer. 4

[Turn over

2. (a) What is the transfer function of a system ? Determine the transfer function of a field controlled D.C servomotor. What is the relationship between torque and angular speed of motor ? 1+5+1=7
- (b) Explain the working principle of synchro transmitter. Derive the output voltage of stator coils of a synchro transmitter. 4+3=7
3. (a) Explain the working principle of an ampli-dyne. 3
- (b) Using block diagram reduction technique, find the closed loop transfer function of the following system. 6



- (c) Convert the following block diagram to signal flow graph and determine the transfer function using Mason's gain formula. 5



4. (a) Define the following : 3
- (i) Unit step signal
 - (ii) Unit impulse signal and
 - (iii) Peak overshoot of an underdamped system.
- (b) Determine the time response of a first order system for a unit step input. What do you mean by steady state error ? 5+1=6
- (c) The response of a servomechanism is $c(t) = 1 + 0.2 e^{-6t} - 1.2 e^{-10t}$ when subject to a unit step input. Obtain an expression for closed loop transfer function. Determine the undamped natural frequency and damping ratio. 5

5. (a) What is the meaning of stability of a system ?
Construct Routh array and determine the stability of the system whose characteristic equation is

$$S^6 + 2S^5 + 8S^4 + 12S^3 + 20S^2 + 16S + 16 = 0.$$

Also determine the number of roots lying on the right half of S-plane, left half of S-plane and on imaginary axis. 1+5=6

- (b) Determine the range of k for stability of unity feedback system whose open loop transfer function is 5

$$G(s) = \frac{k}{S(S+1)(S+2)}$$

- (c) If the open loop transfer function of a system

$$\text{is } G(s) = \frac{k}{S(S+a)},$$

find the ranges of k for which the roots of system is 3

- (i) real and distinct
- (ii) real and equal and
- (iii) are complex conjugate using the concept of root locus.

6. Plot the Bode diagram for the following transfer function and obtain the gain and phase cross over frequencies 14

$$G(s) = \frac{10}{S(1 + 0.4s)(1 + 0.1s)}$$

7. Write short notes on any *four* of the following : 4×3½=14

- (i) Servomechanism
- (ii) Magnetic amplifier
- (iii) AC servomotor
- (iv) Stepper motor
- (v) Synchro control transformer.