

Total number of printed pages-8

53 (EC 302) LSSG

2017

LINEAR SYSTEMS AND SIGNALS

Paper : EC 302

Full Marks : 100

Time : Three hours

The figures in the margin indicate full marks for the questions.

Answer **any five** questions out of **seven**.

1. (a) Represent the following signal in terms of unit-step function. 3

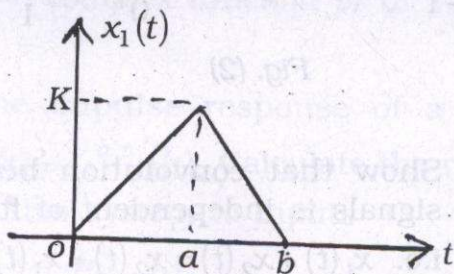


Fig. (1)

Contd.

- (b) Define impulse function. Show how an impulse function be approximated in terms of a rectangular pulse function. Describe the arbitrary signal $x(t)$ in terms of a series of impulse functions.

$$2+2+4=8$$

- (c) The variation of two signals $x_1(t)$ and $x_2(t)$ are given in Fig. (2). Evaluate $x_1(t) * x_2(t)$.

6

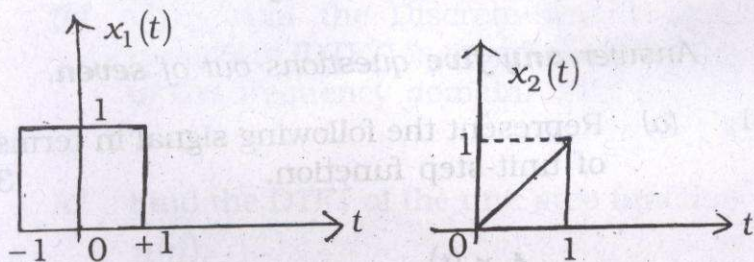


Fig. (2)

- (d) Show that convolution between two signals is independent of its order

i.e. $x_1(t) * x_2(t) = x_2(t) * x_1(t)$.

3

2. (a) Find $x(-2t+1)$ for the signal $x(t)$ shown in Fig. (3). 4

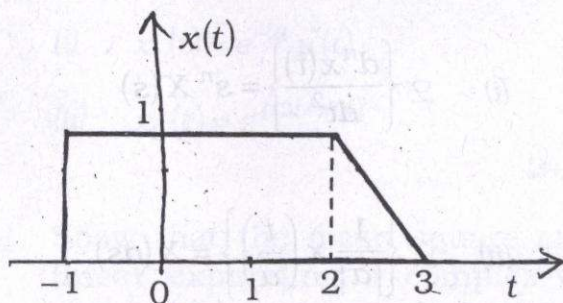


Fig. (3)

- (b) Check whether the following systems are linear and time-invariant.

(i) $y(t) = t \sin(x(t))$

(ii) $y(t) = \text{Re}\{x(t)\}$ where, $x(t)$ is a complex function of t .

2+2=4

- (c) The impulse response of a system $h(t) = e^{-\alpha_1 t} u(t)$. Calculate the response of this system to inputs

(i) $e^{-\alpha_2 t} u(t)$

(ii) $\sin \omega_0 t u(t)$

(iii) $t u(t)$

3×4=12

3. (a) Prove the following if $X(s)$ is the bilateral Laplace transform of $x(t)$

$$(i) \quad \mathcal{L} \left\{ \frac{d^n x(t)}{dt^n} \right\} = s^n X(s)$$

$$(ii) \quad \mathcal{L} \left\{ \frac{1}{|a|} x \left(\frac{t}{a} \right) \right\} = X(as)$$

2x4=8

- (b) Determine the zero-input response and zero-state response of an LTI system represented by the following differential equation.

$$\frac{d^2 y(t)}{dt^2} + 5 \frac{dy(t)}{dt} + 6y(t) = \frac{dx(t)}{dt} + 6x(t)$$

$$\text{Given } y(0^-) = 1 \text{ and } \left. \frac{dy}{dt} \right|_{t=0^-} = 2.$$

8

- (c) State and prove final value theorem.

4

4. (a) Explain how to calculate energy and power of a signal. Determine the energy and power of the signals,

(i) $x_1(t) = e^{-2t} u(t)$

(ii) $x_2(t) = e^{j(2t+\pi/4)}$

2+2+2=6

- (b) Show that the mean square error in linear expanding a complex-valued signal $f(t)$ in terms of an orthogonal set, $\{g_1(t), g_2(t), \dots, g_N(t)\}$ is minimized when the co-efficient of expansion,

$$C_n = \frac{\langle f(t), g_n(t) \rangle}{\langle g_n(t), g_n(t) \rangle} \quad 6$$

- (c) Find the exponential Fourier series and sketch the corresponding line spectrum of a half-wave rectified sine wave shown in Fig. (4). 8

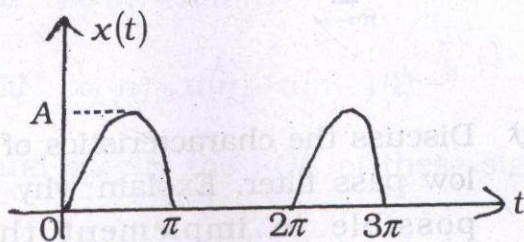


Fig. (4)

5. (a) State and prove Parseval's theorem for power signals. 5

(b) Consider the rectangular pulse signal

$$x(t) = A \operatorname{rect}\left(\frac{t}{2T_0}\right) = \begin{cases} A, & |t| < T_0 \\ 0, & |t| > T_0 \end{cases}$$

Find the Fourier transform of $x(t)$ and plot its magnitude and phase spectrum. 5

(c) Evaluate the Fourier transform of signum function. Using this result find the Fourier transform of $u(t)$, the unit step function. 5

(d) Find and sketch the Fourier transform of the impulse train,

$$x(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT_0). \quad 5$$

6. (a) Discuss the characteristics of an ideal low pass filter. Explain why it is not possible to implement the same practically. 5

(b) Derive the relationship between the real and imaginary parts of the frequency response of a causal system.

5

(c) Show that $x(n) = z^n$ is an eigensignal of a Linear time-invariant discrete-time system. Evaluate the output, $y(n)$ for an LTI system if its impulse

response, $h(n) = \left\{ \underset{\uparrow}{1}, \frac{1}{2}, \frac{1}{4} \right\}$ and input,

$$x(n) = \left\{ \underset{\uparrow}{2}, 4, 8 \right\}. \quad 5$$

(d) Determine the z -transform of

(i) $x_1(n) = n u(n)$

(ii) $x_2(n) = u(n) - u(n - 10)$

and specify the ROC of these signals.

5

7. (a) An LTI system is characterized by the z-transform of the impulse response,

$$h(n) \text{ as } H(z) = \frac{3 - 4z^{-1}}{1 - 3.5z^{-1} + 1.5z^{-2}}.$$

Specify the ROC and determine $h(n)$ for the following conditions :

- (i) The system is causal and unstable
 - (ii) The system is non-causal and stable
 - (iii) The system is anti-causal and unstable. 8
- (b) Show that the Discrete-time Fourier transform (DTFT) is a periodic function in the frequency domain. 4
- (c) Find the DTFT of the unit step function $u(n)$. 8